void setup() {

pinMode(11,OUTPUT);

pinMode(10,OUTPUT);

pinMode(8,OUTPUT);

pinMode(9,OUTPUT);

pinMode(13,INPUT);

}

void loop()

{

if(digitalRead(13)==0)

{

//Lift

digitalWrite(11,LOW);

digitalWrite(10,HIGH);

delay(1500 \*16);

digitalWrite(11,HIGH);

digitalWrite(10,HIGH);

Serial.println("ON");

delay(500\*12);

//cAPPER

digitalWrite(8,LOW);

digitalWrite(9,HIGH);

delay(1000\*6);

//stop capper

digitalWrite(8,HIGH);

digitalWrite(9,HIGH);

delay(1000);

//move lift Up

digitalWrite(11,HIGH);

digitalWrite(10,LOW);

delay(1500\*16);

//STOPEVERYTHING

digitalWrite(11,HIGH);

digitalWrite(10,HIGH);

digitalWrite(8,HIGH);

digitalWrite(9,HIGH);

delay(60000);

}

}